

VECTOR CALCULUS

* Vector calculus deals with two types of vectors

- Constant vector
- Variable vector

↓
Vectors which are constant in magnitude and fixed in direction

↓
Vectors which are varying in magnitude (or) direction (or) in both.

* In vector calculus we deal with fields

- field is one region of space such that every point, P , in this region is specified with a physical property.

* Fields are of two kinds

Scalar field

FIELDS

Vector field

- Scalar field is the one where the physical property associated with every point is expressed as scalar quantity.

- This scalar quantity will have different values at different points.

- Its value at any point, P , will depend on the co-ordinates of P .

- Hence it is called Scalar point function

- example: Temperature of a swimming pool.

- vector field is the one where the physical property associated with every point is expressed as vector quantity.

- Example: → The velocity at all the points of a moving fluid
- The velocity, at every point, will be represented by a continuous vector function.

- At every point this vector function is specified by a vector with certain magnitude and direction

- Hence it is called Vector point function

* VECTOR DIFFERENTIAL OPERATOR:

The vector operator, ∇ (del) is defined as

$$\nabla \equiv \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$$

- It possesses properties analogous to those of ordinary vectors as well as differential operators.
- It is useful in defining
 - Gradient
 - The divergence
 - The curl.

* GRADIENT OF A SCALAR POINT FUNCTION:

- Let $\phi(x, y, z)$ be a scalar point function defined in some region of space. Then the corresponding vector point function, $\vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z}$ is known as the gradient of ϕ and is denoted by $\text{grad } \phi$.

$$\begin{aligned} \text{grad } \phi &= \vec{i} \frac{\partial \phi}{\partial x} + \vec{j} \frac{\partial \phi}{\partial y} + \vec{k} \frac{\partial \phi}{\partial z} \\ &= \left(\vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z} \right) \phi \end{aligned}$$

$$\text{grad}(\phi) = \nabla \phi$$

- $\nabla \phi$ defines a vector field.
 - If ϕ is constant, then $\nabla \phi = 0$.
- (1.2) $\frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial y} = \frac{\partial \phi}{\partial z} = 0$.

- $\nabla(u+v) = \nabla u + \nabla v$
 - $\nabla(uv) = u \cdot \nabla v + v \cdot \nabla u$
 - If $v = f(u)$ then $\nabla v = \nabla(f(u)) = f'(u) \cdot \nabla u$
- where u and v are two scalar point functions.

* DIRECTIONAL DERIVATIVE OF A SCALAR POINT FUNCTION.

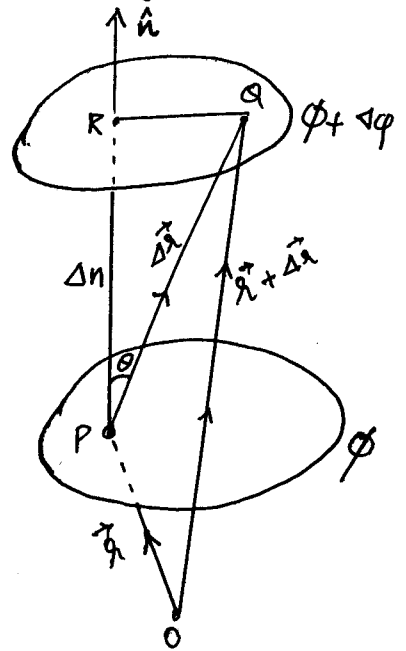
- Let $\phi(x, y, z)$ be a scalar point function defined in some region.
- Let P and Q be two neighbouring points in that region.
- Whose position vectors be $\vec{OP} = \vec{r}$ and $\vec{OQ} = \vec{r} + \Delta\vec{r}$ w.r.t origin O.
- Let (ϕ) and $(\phi + \Delta\phi)$ be the values of the S.P.F at P and Q respectively.

• Let Δr be the length of the vector $\Delta\vec{r}$.

• $\frac{\Delta\phi}{\Delta r}$ is the measure of the rate at which ϕ changes when we move from P to Q.

• The limiting value of this ratio, $\frac{\Delta\phi}{\Delta r}$ as $\Delta r \rightarrow 0$ is called directional derivative of ϕ , in the direction PQ.

(i.e) directional derivative of $\phi = \lim_{\Delta r \rightarrow 0} \frac{\Delta\phi}{\Delta r} = \frac{d\phi}{dr}$.



* LEVEL SURFACES:

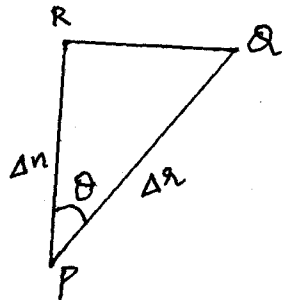
• The surfaces passing through any arbitrary point P such that, at each point on it, the value of the scalar point function will remain same as in P, is called level surface.

• Consider two such level surfaces passing through P and Q. Let the normal at P, meet the level surface through Q at the point R. Let $PR = \Delta n$ (least distance betn surfaces)

$\frac{d\phi}{dn} \rightarrow$ rate of change of ϕ along normal, PR.

$\frac{d\phi}{dr} \rightarrow$ rate of change of ϕ along \vec{PQ} .

• If $\angle \hat{P}R = \theta$, $\cos \theta = \frac{\Delta n}{\Delta r} \Rightarrow \Delta n = \Delta r \cdot \cos \theta$



• We can write $\frac{d\phi}{dr} = \frac{d\phi}{dn} \cdot \frac{dn}{dr}$

$$= \frac{d\phi}{dn} \cdot \cos \theta$$

As $\cos \theta \leq 1$, we have $\frac{d\phi}{dr} \leq \frac{d\phi}{dn}$ \rightarrow (*)

• (*) \Rightarrow The rate of increase of ϕ along the direction \vec{PQ} is always less than that along the normal at P.

• At any point the rate of increase of ϕ is greatest only along the normal at the point than any other direction.

* Let \hat{n} be the unit vector along the normal at P.

• Then $\hat{n} \cdot \Delta \vec{r} = |\hat{n}| \cdot |\Delta \vec{r}| \cos \theta$

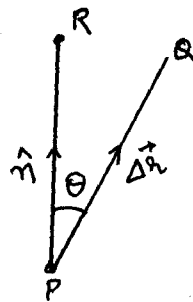
$$= 1 \cdot \Delta r \cos \theta$$

(i.e) $\Delta r \cos \theta = \hat{n} \cdot \Delta \vec{r}$ — (1)

but $\Delta r \cos \theta = \Delta n$ (refer (**))

\downarrow (2)

using (2) in (1) we get $\Delta n = \hat{n} \cdot \Delta \vec{r}$ — (3) $\Rightarrow dn = \hat{n} \cdot d\vec{r}$



• Now we can write $d\phi = \frac{d\phi}{dn} \cdot dn \Rightarrow d\phi = \frac{d\phi}{dn} \hat{n} \cdot d\vec{r}$ — (4)

• but $d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz$

$d\phi = \vec{\nabla} \phi \cdot d\vec{r}$ — (5) equating (4) & (5)

$\vec{\nabla} \phi \cdot d\vec{r} = \frac{d\phi}{dn} \hat{n} \cdot d\vec{r}$

$\Rightarrow \vec{\nabla} \phi = \frac{d\phi}{dn} \hat{n}$ — (6)

* ⑥ $\Rightarrow \nabla\phi$ is a vector in the direction \hat{n} and its magnitude is $\frac{d\phi}{dn}$ and we know this is the greatest rate of increase of ϕ .

⑦ So we conclude, the gradient of scalar point function, $\phi(x, y, z)$, is a vector along a normal to the level surface $\phi(x, y, z) = C$ and its magnitude is the greatest increase of ϕ , namely, $\frac{d\phi}{dn}$.

* ⑧ Since $\frac{d\phi}{dr} = \frac{d\phi}{dn} \cos\theta$, the directional derivative of the function (ϕ) in any arbitrary direction is the projection of the gradient of the function in that direction.

⑨ Directional derivative of a function is maximum along the direction of $\nabla\phi$.

* Problem: \rightarrow In what direction, from the point $(-1, 1, 2)$, is the directional derivative of $\phi = xy^2z^3$ a maximum? What is its magnitude?

Solution: We know that directional derivative is maximum along $\nabla\phi$

$$\therefore \text{Let us find } \nabla\phi, \text{ w.k.t } \nabla\phi = \hat{i} \frac{\partial\phi}{\partial x} + \hat{j} \frac{\partial\phi}{\partial y} + \hat{k} \frac{\partial\phi}{\partial z} \quad \text{--- (1)}$$

$$\text{Given } \phi = xy^2z^3 \quad \therefore \frac{\partial\phi}{\partial x} = y^2z^3; \quad \frac{\partial\phi}{\partial y} = 2xyz^3; \quad \frac{\partial\phi}{\partial z} = 3xy^2z^2;$$

$$\text{using in (1) we get, } \nabla\phi = \hat{i}(y^2z^3) + \hat{j}(2xyz^3) + \hat{k}(3xy^2z^2)$$

$$\left(\nabla\phi \right)_{(-1, 1, 2)} = \underline{\underline{8\hat{i} - 16\hat{j} - 12\hat{k}}} \quad \text{--- (2)}$$

∴ for given $\phi = xy^2z^3$, the directional derivative will be maximum 6

along $\nabla\phi = 8\vec{i} - 16\vec{j} - 12\vec{k}$.

Its magnitude is $|\nabla\phi| = \sqrt{(8)^2 + (-16)^2 + (-12)^2} = \sqrt{404} = \underline{\underline{2\sqrt{101}}}$ units

Problem:

Find the directional derivative of $\phi = x^2yz + 4xz^2$ at $(1, -2, -1)$ in the direction of $2\vec{i} - \vec{j} - 2\vec{k}$.

Soln:

Given $\phi = x^2yz + 4xz^2 \rightarrow \frac{\partial\phi}{\partial x} = 2xyz + 4z^2$; $\frac{\partial\phi}{\partial y} = x^2z$;

$\frac{\partial\phi}{\partial z} = x^2y + 8xz \quad \therefore \nabla\phi = \vec{i}(2xyz + 4z^2) + \vec{j}(x^2z) + \vec{k}(x^2y + 8xz)$

$(\nabla\phi)_{(1, -2, -1)} = 8\vec{i} - \vec{j} - 10\vec{k}$

Directional derivative of ϕ is the projection of $\nabla\phi$ in the given direction

W.K.T. Projection of $\nabla\phi$ on $2\vec{i} - \vec{j} - 2\vec{k}$ is

$$\begin{aligned} & \frac{\nabla\phi \cdot (2\vec{i} - \vec{j} - 2\vec{k})}{|2\vec{i} - \vec{j} - 2\vec{k}|} \\ &= \frac{(8\vec{i} - \vec{j} - 10\vec{k}) \cdot (2\vec{i} - \vec{j} - 2\vec{k})}{|2\vec{i} - \vec{j} - 2\vec{k}|} \\ &= \frac{16 + 1 + 20}{\sqrt{4 + 1 + 4}} = \frac{37}{3} \end{aligned}$$